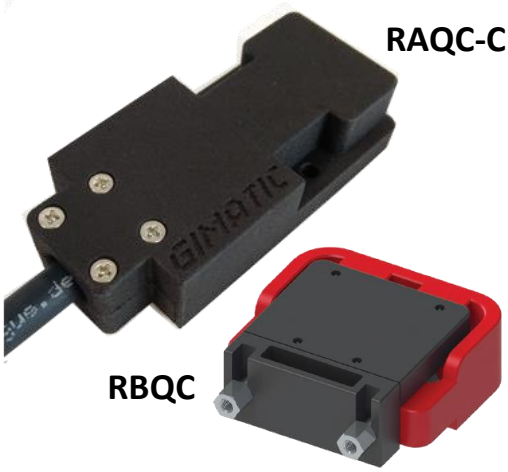
DESCRIPTION

Automatic recognition system of gripping tool (or EOAT) composed of a RFID reader RAQC-C (PNP version) and one or more memory TAGs RBQC.
Main characteristics:

- customizable cable output of the reader module for reliable application using serial robots and cable carriers;
- up to 255 identifiable tools with a single TAG;
- binary coding of tools by means of 8 digital output signals (24Vdc);
- digital input to counting tool cycles execution (stored in TAG memory);
- memorization of tool technical data and user data memory available.



SPECIFICATIONS

	RAQC-C	RBQC
Frame	Nylon PA12	Polycarbonate, glass fibre reinforced
Working distance	< 10 mm	
Working frequency	13.56 MHz	
Allowed temperature range	-20÷65°C	
Dimensions box	72 mm x 34 mm x 17 mm	45 mm x 42 mm x 15 mm
Weight	30 g	10 g
Electrical connection	cable output (max outer ø 10 mm)[#]	none
Environmental degree	IP40	IP67
Power supply	24 Vdc ± 10%, 0.15 Arms	none
Communication interface	RS232	none
Memory type	None	MIFARE DESFire EV2 4k
Output signals	10 digital (PNP)	none
Input signals	1 digital (PNP)	none
CE reference norm	EN 60950 2001, EN 300330-2 V1.3.1, EN 301489-1-3 V1.4.1	

[#] *The plastic housing has been designed to accommodate the cable CF9.02.12 by IGUS (8 [mm] as maximum outer diameter) as standard thus allowing connections for only 12 out of the 15 available pins of the circuit board. However, the housing can be easily re-machined to enlarge the correctly tight cable with external diameter up to 10 [mm].*

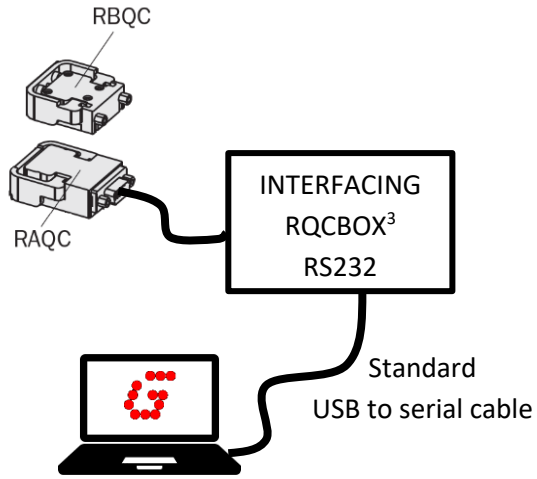
ELECTRIC CONNECTIONS

Pin Name	Description
Vcc	Power Supply 24 Vdc
GND	Power Supply GND
OCNT	Digital output (maintenance alarm) (when set, tool executed the predefined working cycles)
FLT	Digital output (fault condition)
ICNT	Digital input (cycle completed triggering signal) (+1 executed cycle per any rising edge of this signal)
TX	RS232 Tx signal (only for TAG configuration – optional use)
RX	RS232 Rx signal (only for TAG configuration – optional use)
O1	Digital output #1 (bit 1 of the binary code of tool ID) - LSb
O2	Digital output #2 (bit 2 of the binary code of tool ID)
O3	Digital output #3 (bit 3 of the binary code of tool ID)
O4	Digital output #4 (bit 4 of the binary code of tool ID)
O5	Digital output #5 (bit 5 of the binary code of tool ID)
O6	Digital output #6 (bit 6 of the binary code of tool ID)
O7	Digital output #7 (bit 7 of the binary code of tool ID)
O8	Digital output #8 (bit 8 of the binary code of tool ID) – MSb

PRINCIPLE OF OPERATION

The primary context of application of the system is the automatic handling of components. Usually to this purpose a robot is used in combination with several EOATs (End Of The Arm Tools) anyone dedicated to a specific operation. In a similar application the robot wrist may be equipped with a reader unit (RAQC-C/RAQC/RAQCN) and any EAOT may be equipped with a TAG memory component (RBQC). During the setup of the application any single TAG can be filled up with EAOT specific information (by using a smartphone with the dedicated APP[1] or a software PC[2] with a dedicated interfacing box) such as an identification number (ID), mass or geometrical proprieties and a part list. All these data are permanently stored into the TAG memory and some of them are eventually updated by the reader unit during normal operation. Whenever the reader approaches a specific TAG the binary representation of the TAG's ID is generated on 8 digital output pins (DO_1…DO_8) allowing the robot to verify the correspondence of the installed EOAT with the programmed task. A specific digital input signal (DI_Count) is also available to counting the number of cycles executed by the EOAT (i.e. signal coming from a sensorbox) allowing the implementation of predictive maintenance.

TAG interaction with smartphone



TAG interaction with PC application

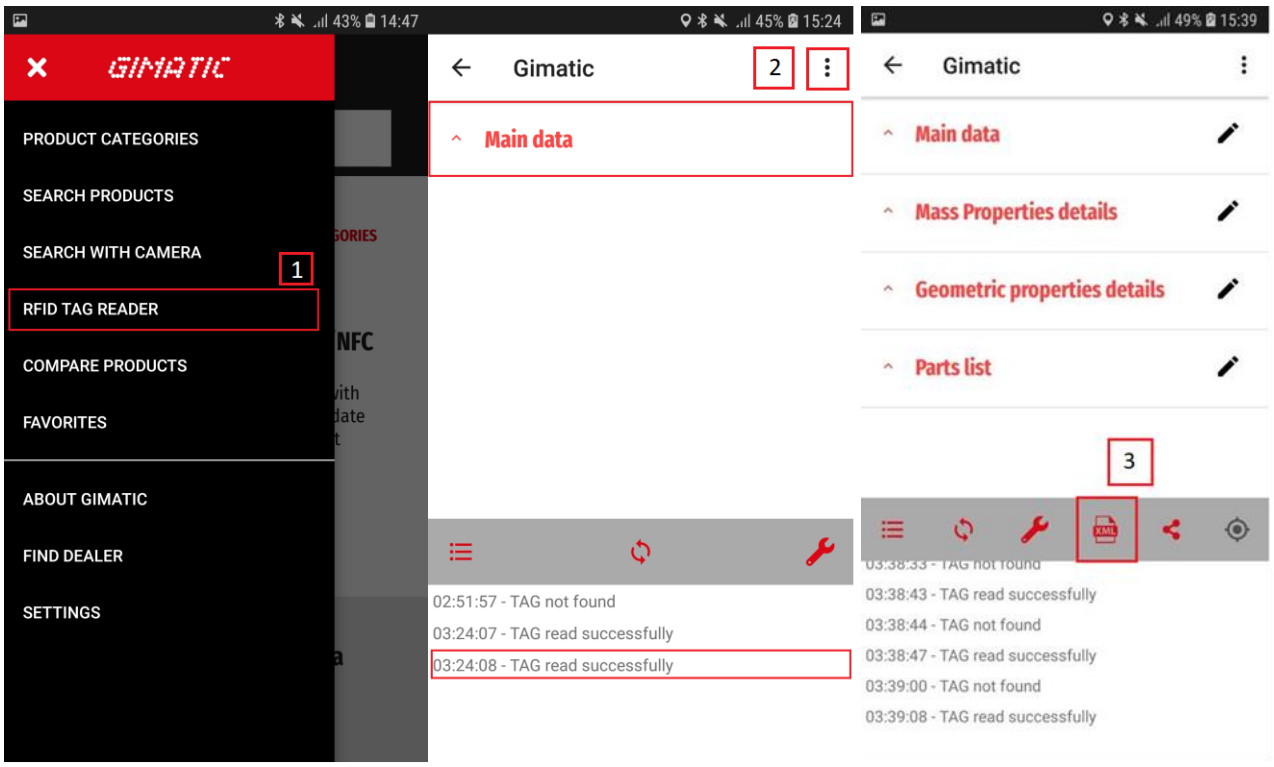
DATA MEMORY OF THE TAG

The memory of the TAG is divided into several data groups and the following information can be stored into and retrieved from the TAG. Additional memory space is available upon request to store custom data.

- MAIN DATA (i.e. tool name and description, tool ID number, tool mass and overall dimensions, etc);
- MASS PROPERTIES (i.e. tool principal moments of inertia, tool centre of gravity coordinates, etc);
- GEOMETRIC PROPERTIES (i.e. geometric calibration parameters);
- PARTS LIST (i.e. up to 40 entries as parts list with editable description, quantity and edition).

[1]Only smartphones with Android O.S. are currently supported. Download Gimatic APP for free from your Store to interact with the TAG (a registration of the APP might be necessary). [2]A dedicated Windows® based application can be downloaded for free from Gimatic website (www.gimatic.com). [3]Available as separate product.

APP PREVIEW

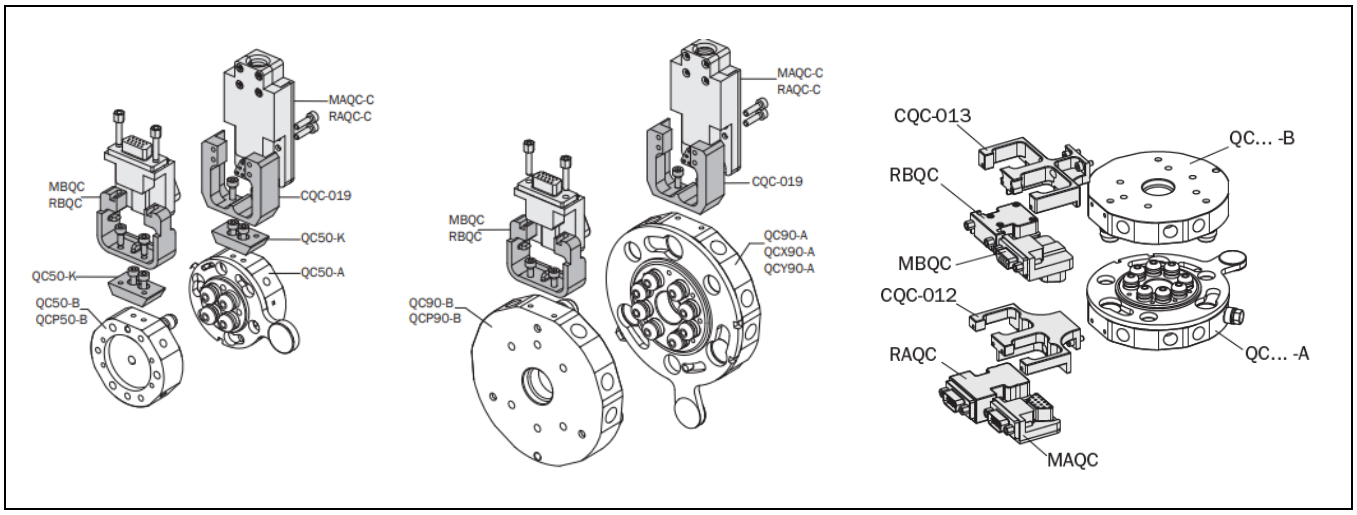


Once the APP has been downloaded and installed from the store, access NFCtag functionality (1) from main menu on the left. Anonymous users have read only access permissions to the MAIN DATA group. Registered users can access the Expert mode (2) with read and write permissions of all the data fields. It's also possible to import and export XML formatted files (3) with an image of the data memory of the TAG to simplify data sharing between several users and between smartphone and PC based applications.

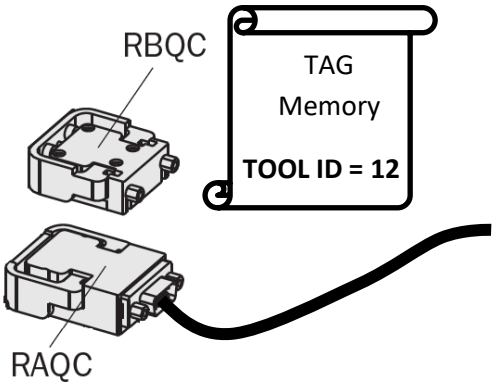
Scan the following QRcode to download the Android application from the Google PlayStore.

APPLICATION EXAMPLES

The following pictures show the application of the RFID system in association with manual tool changers.

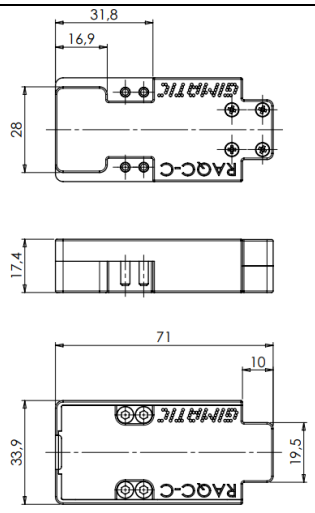
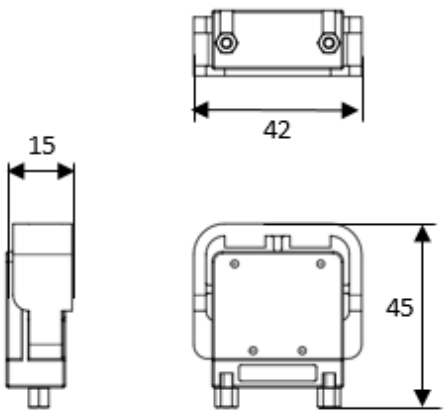


AUTOMATIC TOOL RECOGNITION EXAMPLE (RAQC – PNP OUTPUT TYPE)



DB 15 connector (DO pin # only)							
DO_1	DO_2	DO_3	DO_4	DO_5	DO_6	DO_7	DO_8
0	0	1	1	0	0	0	0
LOW	LOW	HIGH	HIGH	LOW	LOW	LOW	LOW

DIMENSIONAL DRAWINGS

RAQC-C	RBQC
	

APPLICATION EXAMPLES

The following picture shows the application of RFID system useful for storing gripper cycles in the RBQC tag.
The SBM output signal is connected to the DI_Count pin of the RAQC.